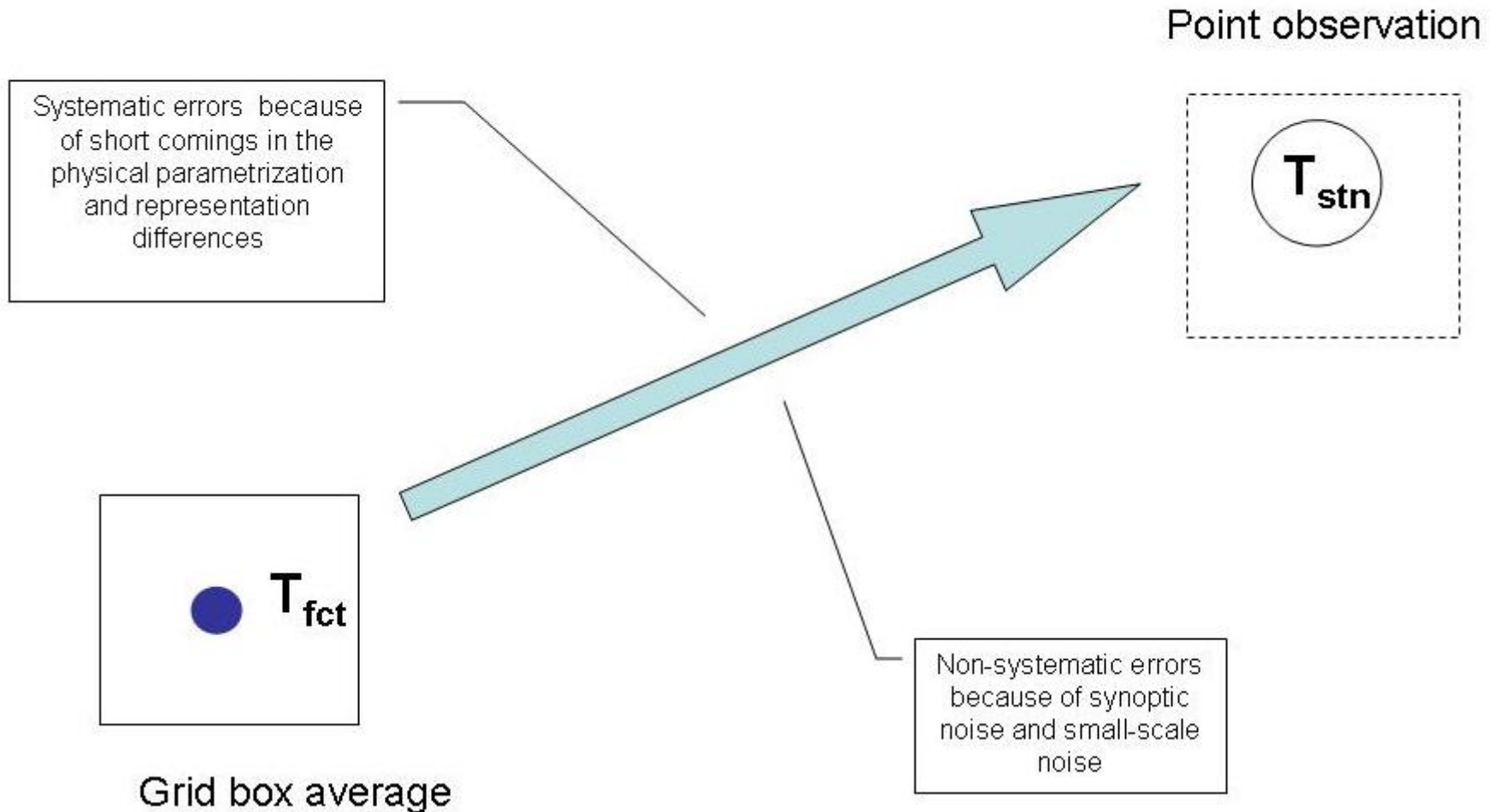
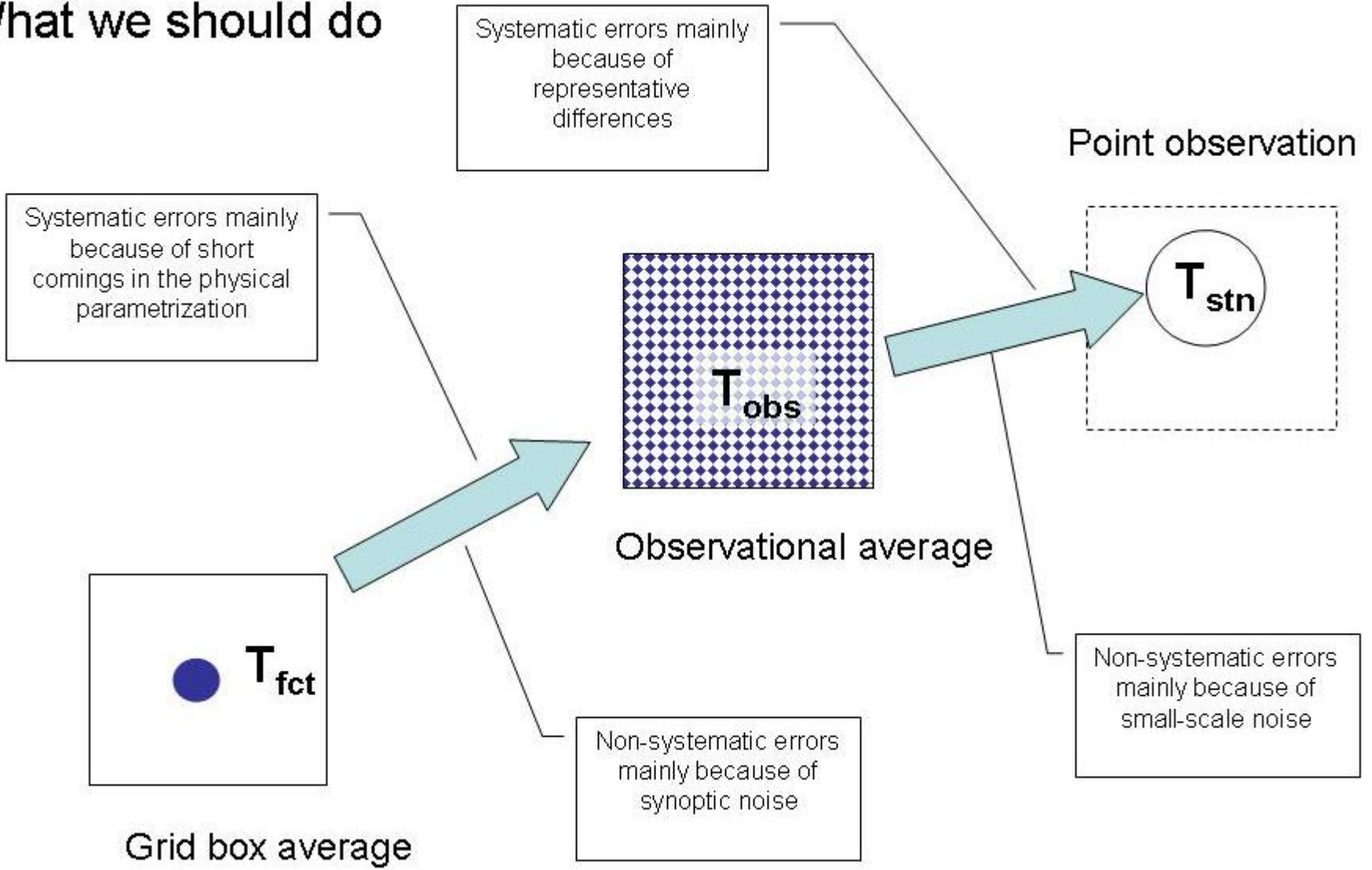


Statistical interpretation of Numerical Weather Prediction (NWP) output

What we do



What we should do



Four types of errors:

Systematic errors

Model errors

Representativeness

Non-systematic errors

Synoptic errors

Small scale “noise”

Four types of errors:

Systematic errors

Model errors

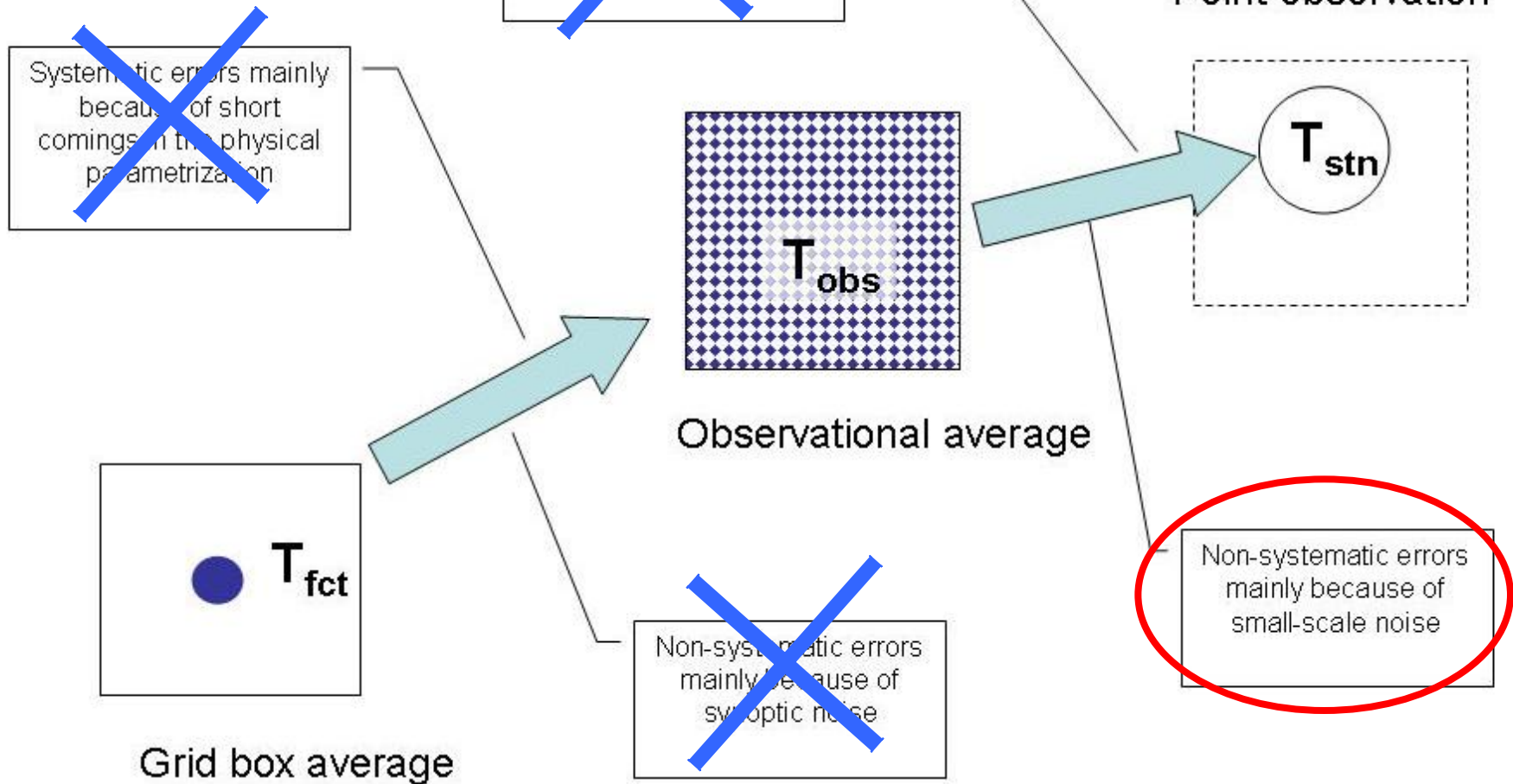
Representativeness

Non-systematic errors

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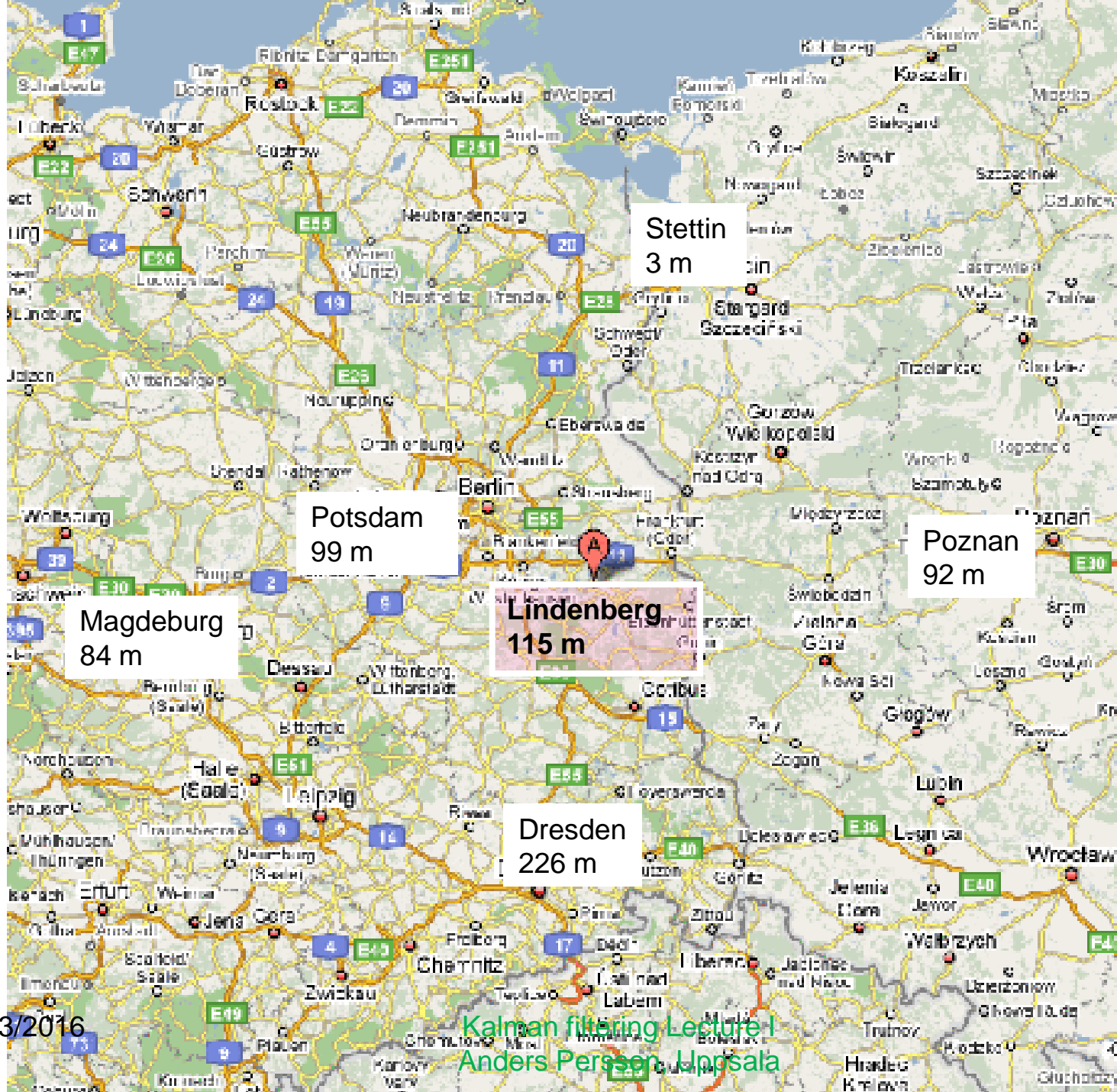
What we should do



Even when we get rid of systematic errors, make the synoptic forecast perfect and only verify against representative observations – the meso-scale “noise” will still yield “non-perfect” forecasts

The two neighbouring stations Potsdam and Lindenberg outside Berlin are just 75 kilometres apart and are situated in almost the same environment. **How well would a “forecast” based on the other one’s observation verify?**

Other nearby stations were also used (Magdeburg, Dresden, Poznan and Stettin). They provided, together with the previous two data to calculate an average temperature as “forecast”.

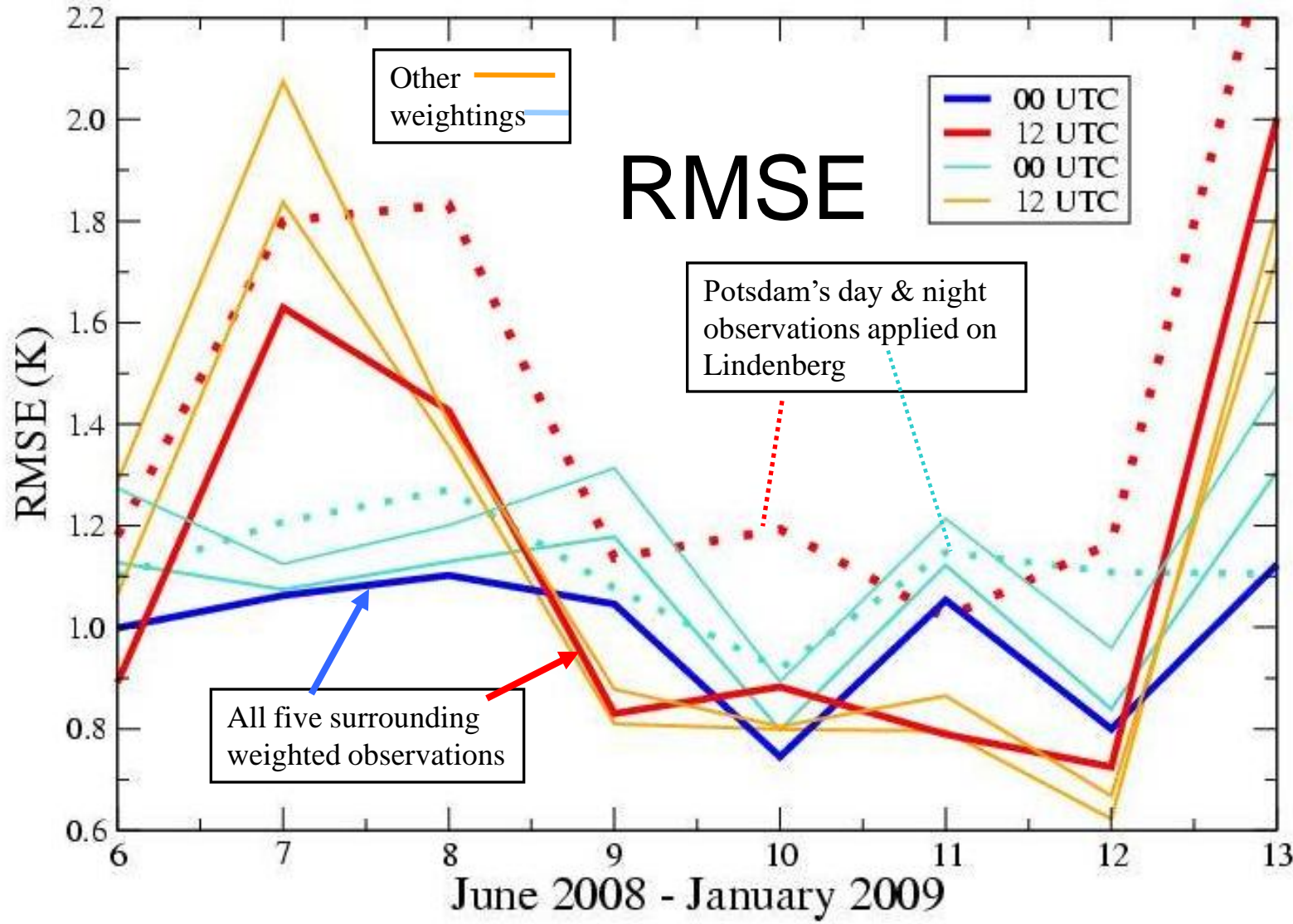


Four tests were conducted all with the objective to estimate (“forecast”) the temperature at Lindenberg:

1. Using the observation from Potsdam as “forecast”
2. Using an average of all five surrounding stations
3. The same but with weights proportional to the square of the distance from Lindenberg
4. The same, but without using the observation from nearby Potsdam

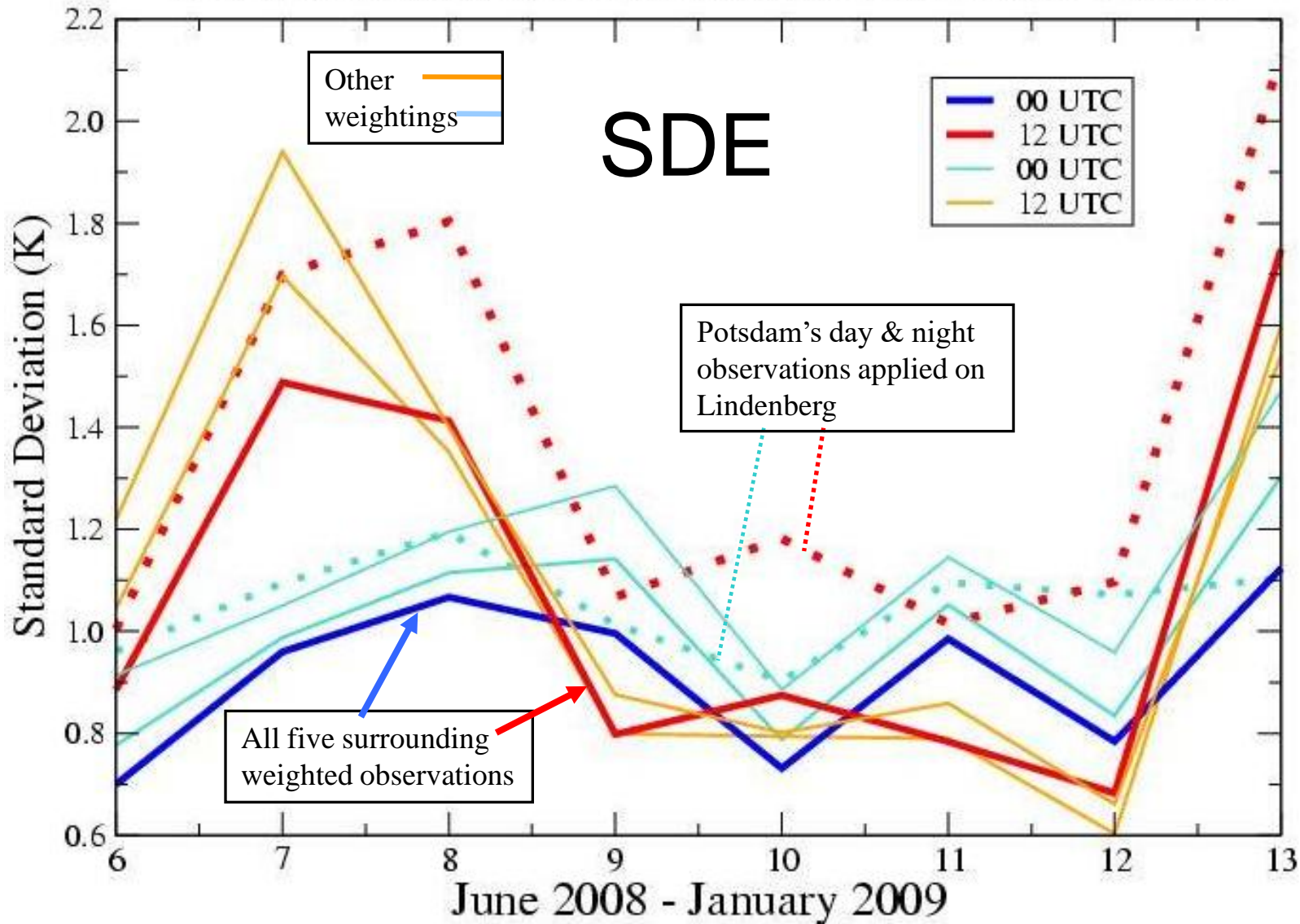
What is the lowest possible 2 m temperature forecast error?

Estimating the 2 m temperature at Lindenberg (SE Berlin) with different methods



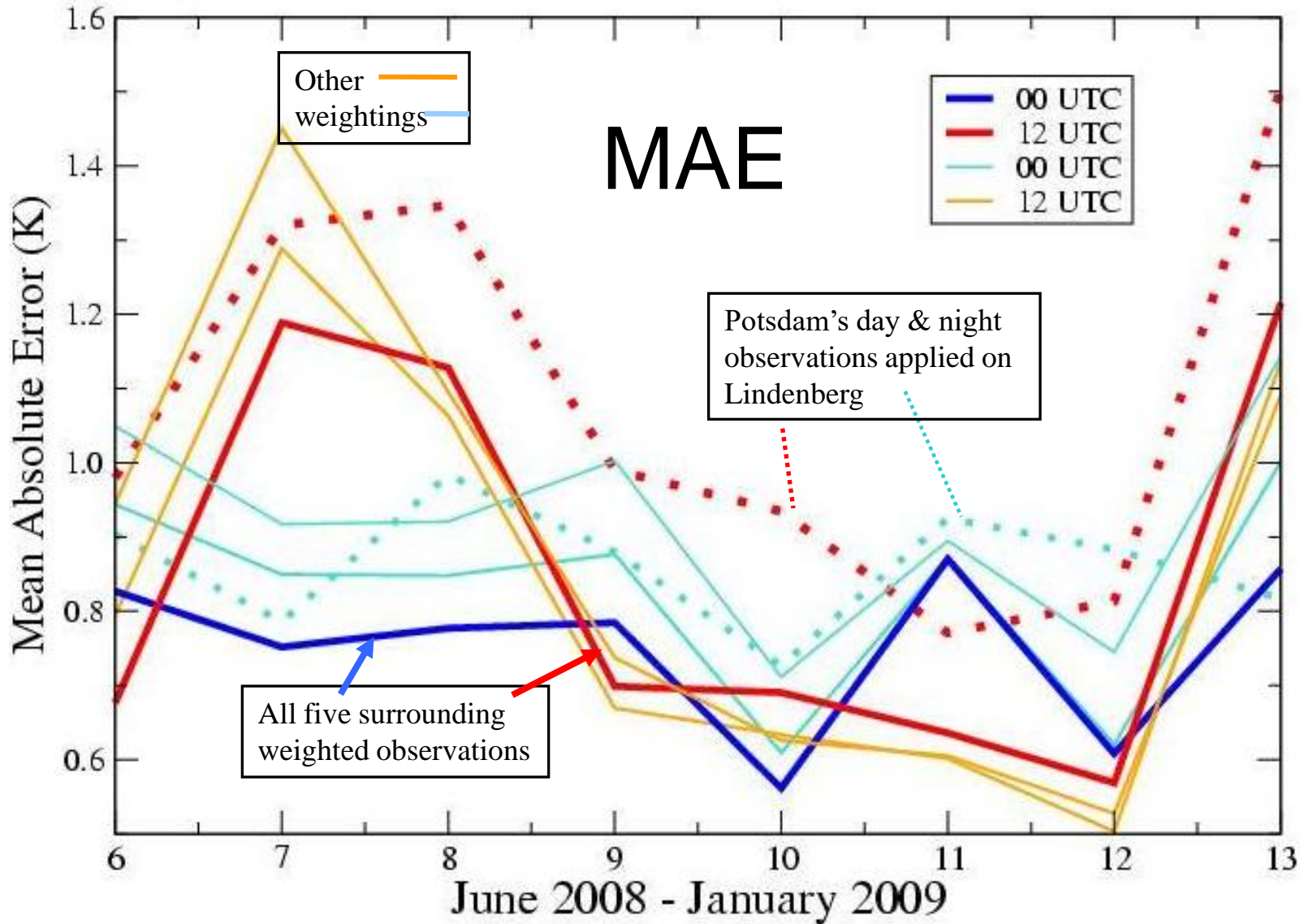
What is the lowest possible 2 m temperature forecast error?

Estimating the 2 m temperature at Lindenberg (SE Berlin) with different methods



What is the lowest possible 2 m temperature forecast error?

Estimating the 2 m temperature at Lindenberg (SE Berlin) with different methods



Conclusions from this observation investigation:

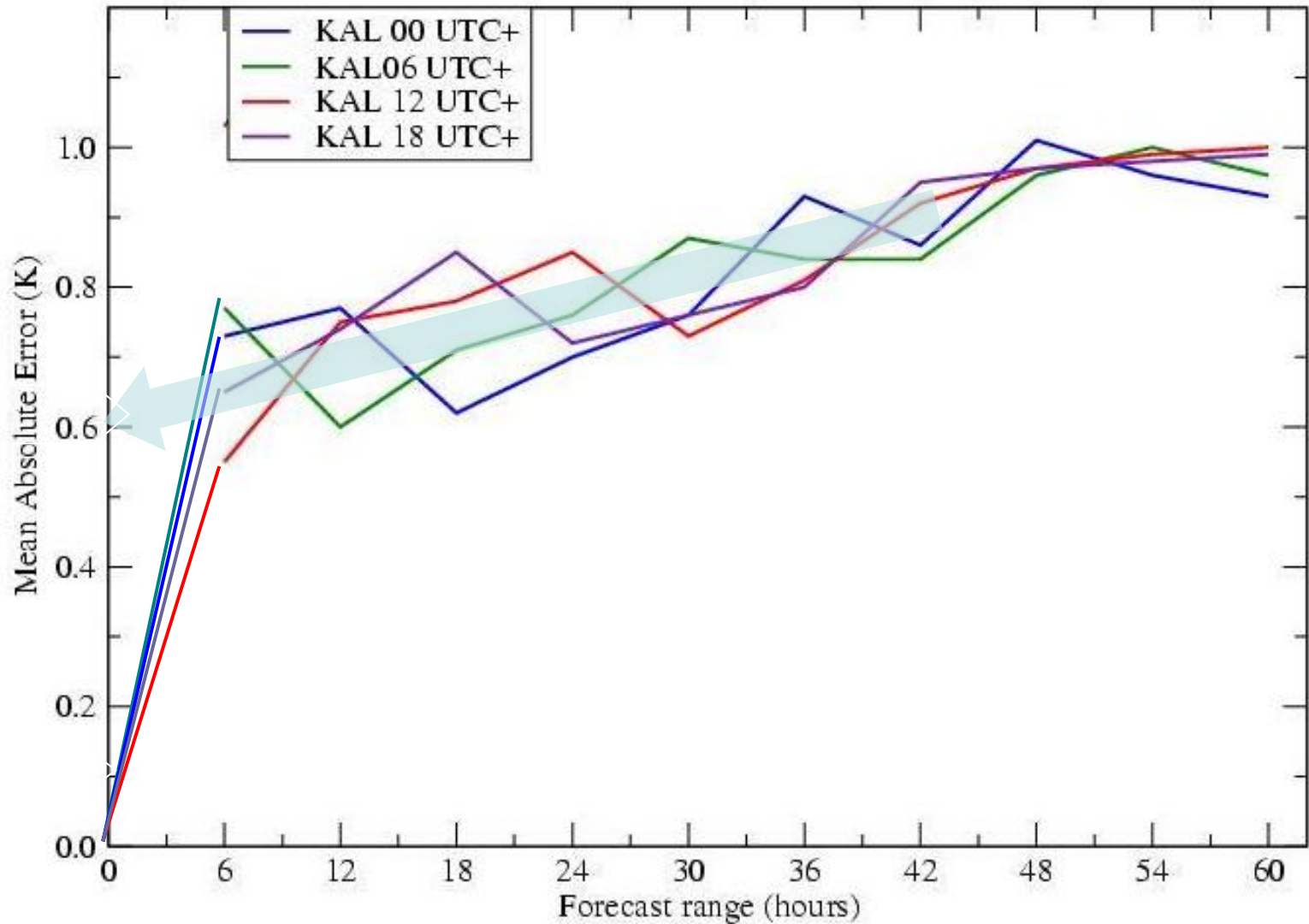
1. During favourable conditions the lowest RMSE and SDE would be around 0.8°K , for MAE 0.6°K
2. During seasons when the temperature depends quite a lot on the clouds the values increase to around 2°K resp. $1\frac{1}{2}^{\circ}\text{K}$.
3. Verified against a specific site, the weighted area average (3) provided the best “forecast”, whereas the neighboring station observation method (1) provided the worst.

Conclusions for all kinds of forecasts beyond a few hours:

1. Due to micro-scale variability the 2 metre temperature is at present not possible to forecast with higher accuracy than 0.8°K (RMSE,SDE) or 0.6°K (MAE).
2. Provided homogenous environment an area average forecast, applied to a specific site, might be superior to a “site specific” .
3. “Site specificness” only has meaning if the site is not representative to the area, if its climate is different to the area as a whole.

Verification of Kalman-2 filtered 2 m temperature forecasts

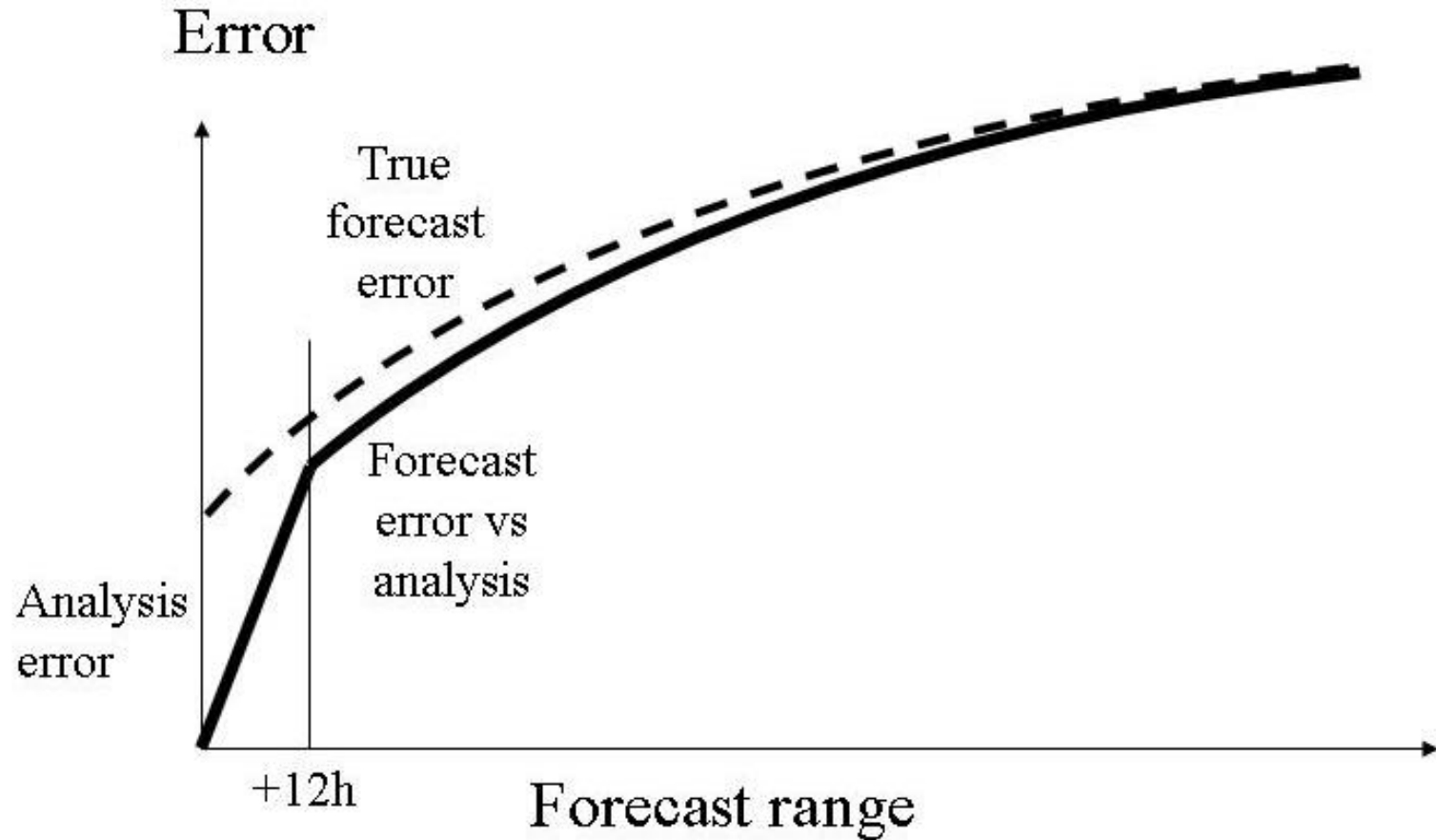
London Weather Centre 10 Oct 2008- end of Febr 2009



Rather
0.6°

Error=0
at t=0?

True and “false” error curves



Four types of errors:

Systematic errors

Model errors

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Synoptic errors

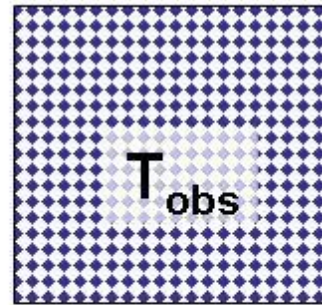
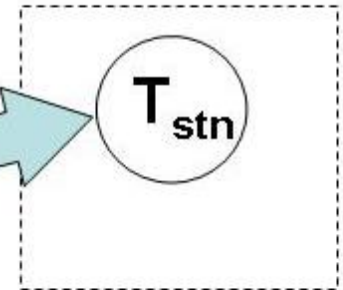
Small scale “noise”

What we should do

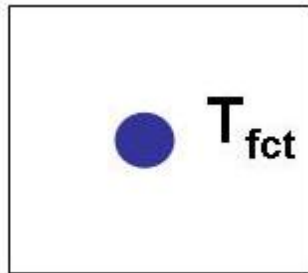
~~Systematic errors mainly because of shortcomings in the physical parametrization~~

~~Systematic errors mainly because of representative differences~~

Point observation



Observational average

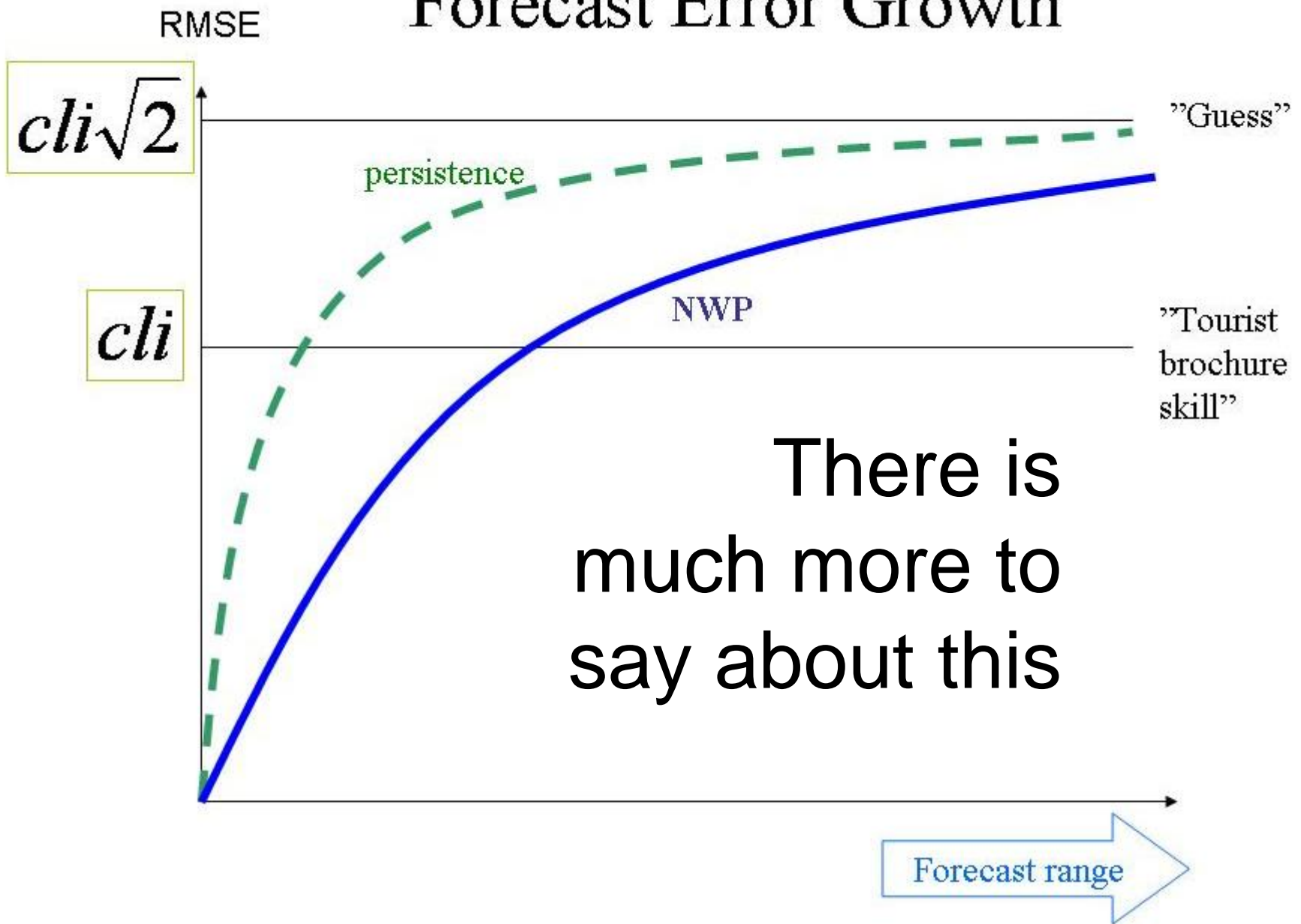


Grid box average

Non-systematic errors mainly because of synoptic noise

~~Non-systematic errors mainly because of small scale noise~~

Forecast Error Growth



Four types of errors:

Systematic errors

Model errors

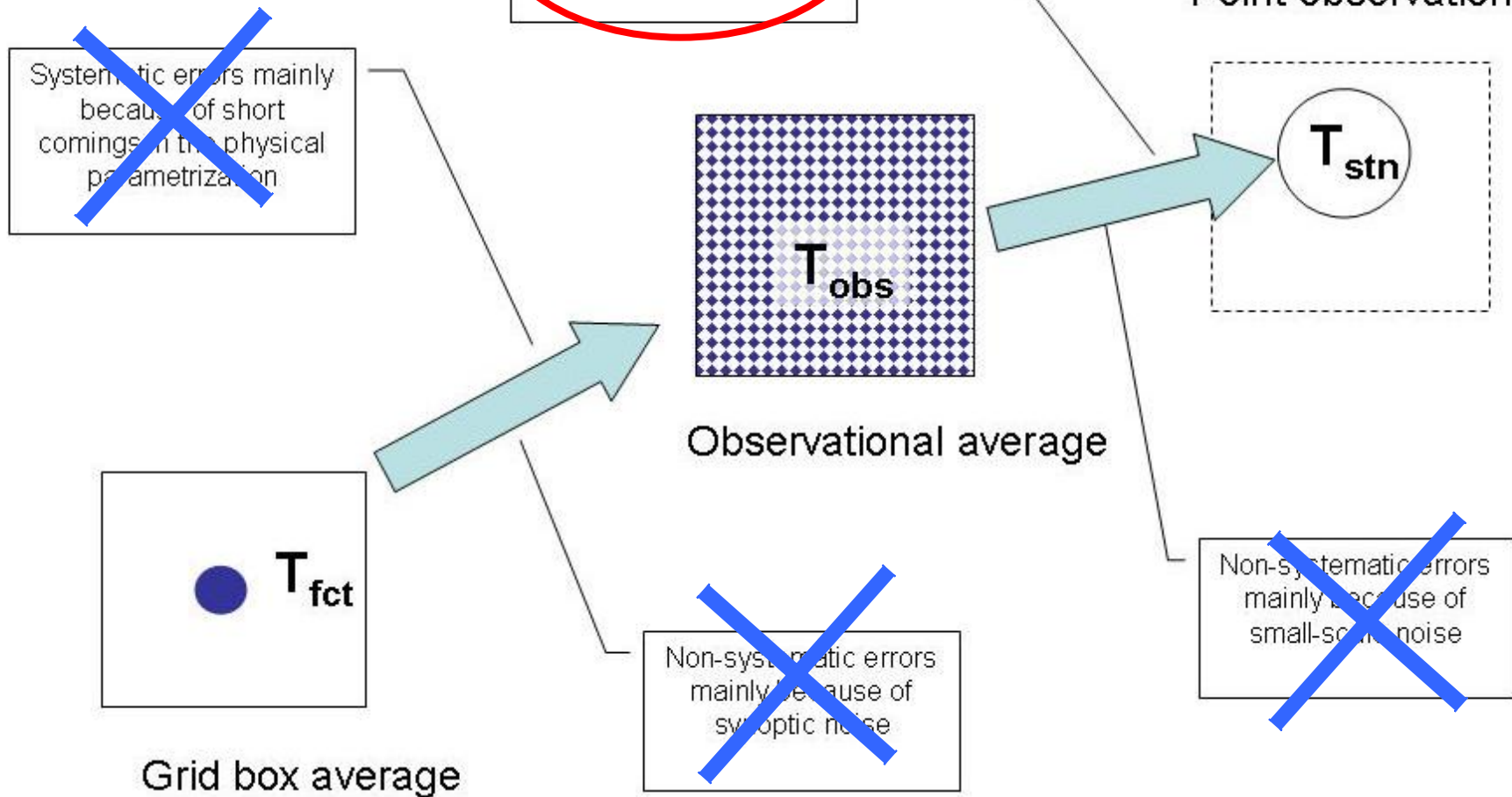
Representativeness

Non-systematic errors

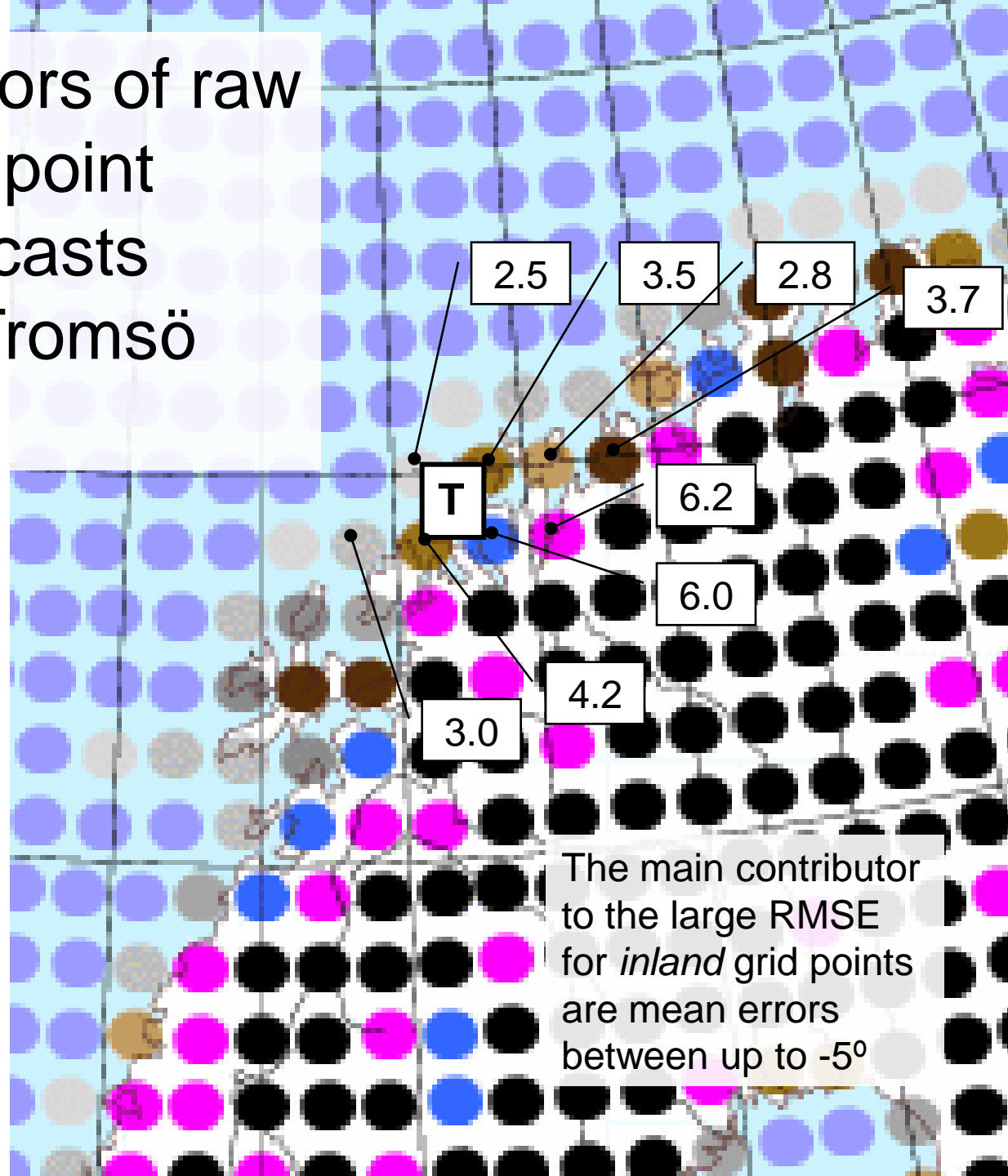
Synoptic errors

Small scale “noise”

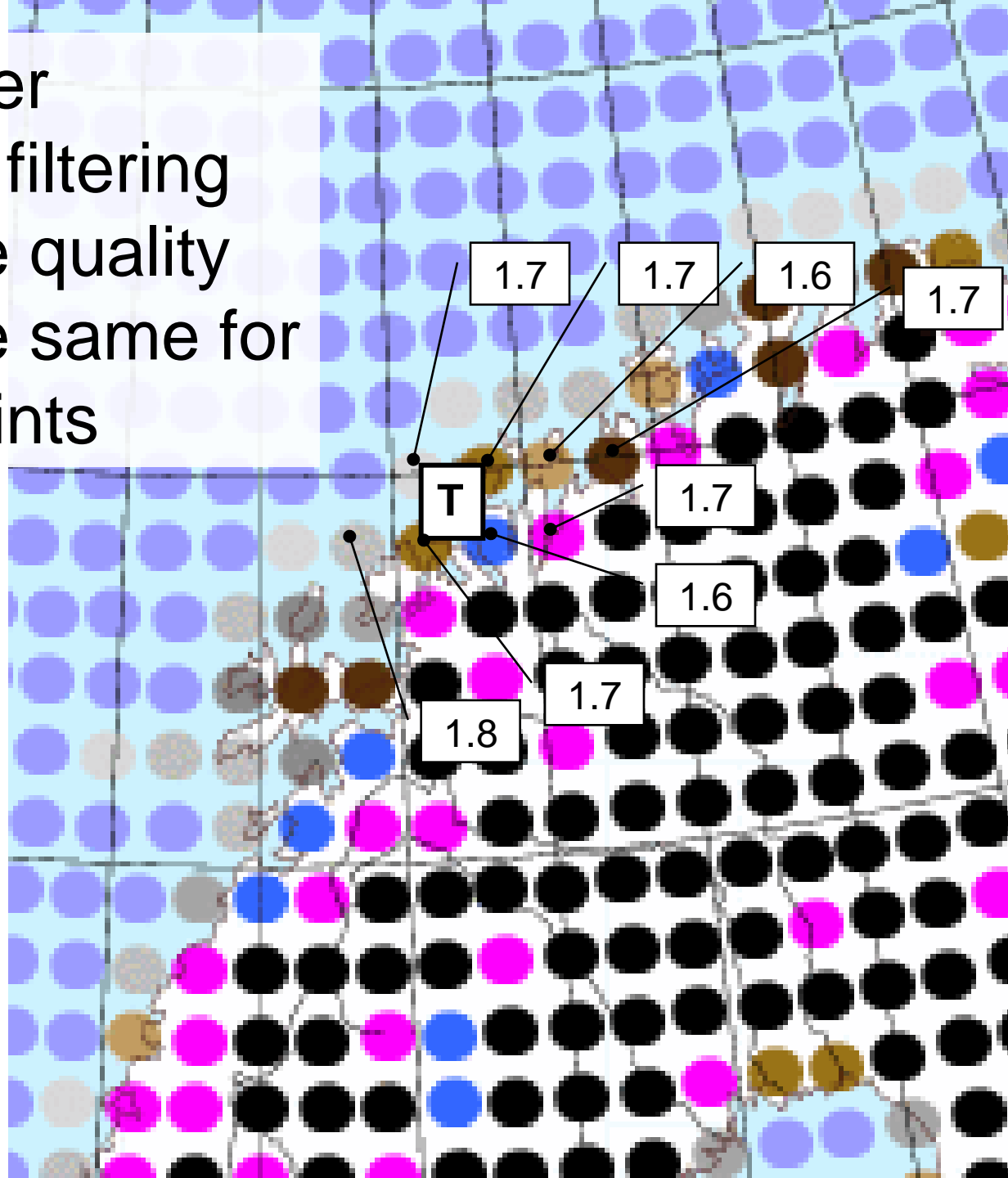
What we should do



RMSE errors of raw
T399 grid point
+24h forecasts
2007 for Tromsø
airport [T]

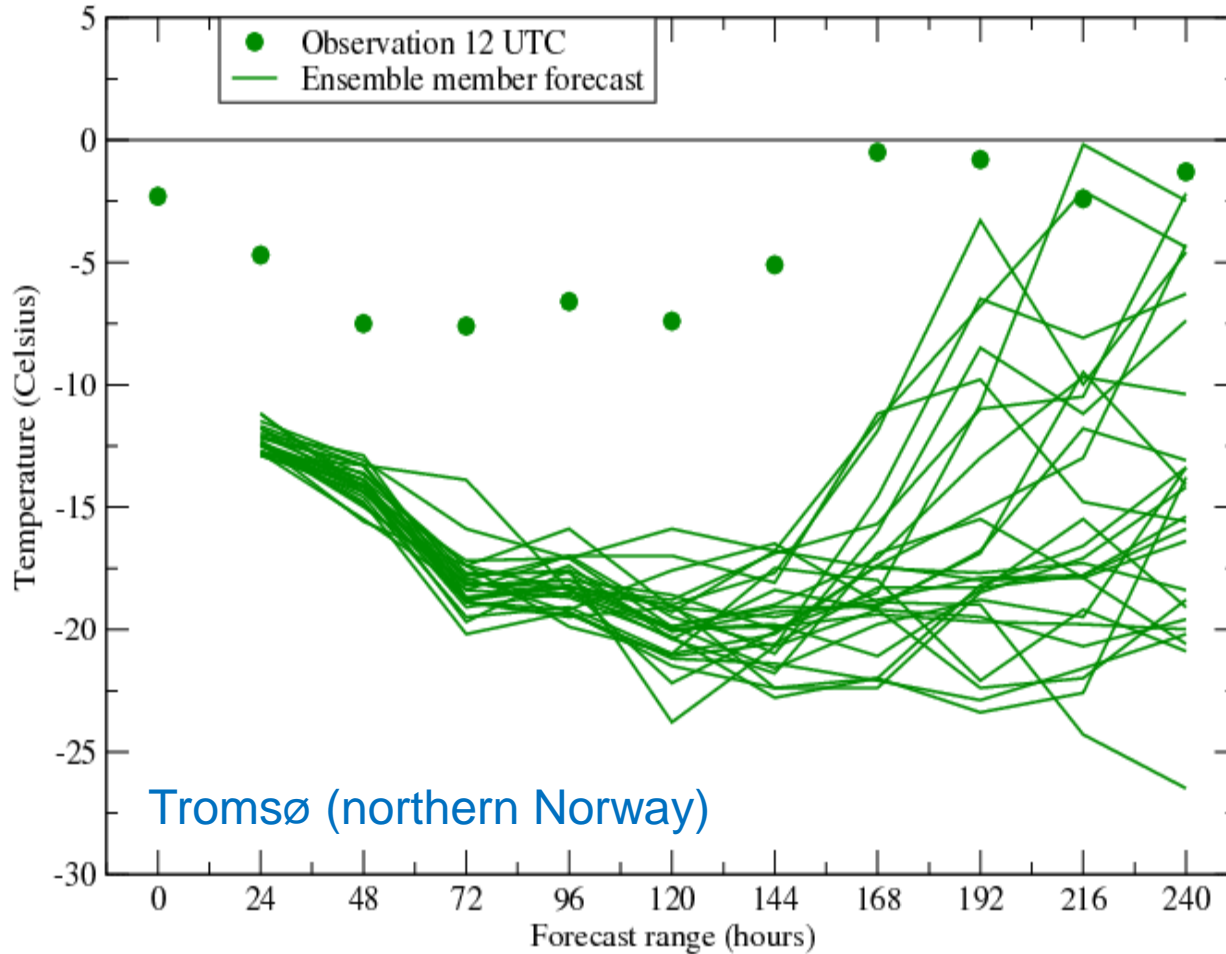


RMSE after
Kalman-2 filtering
makes the quality
almost the same for
all grid points

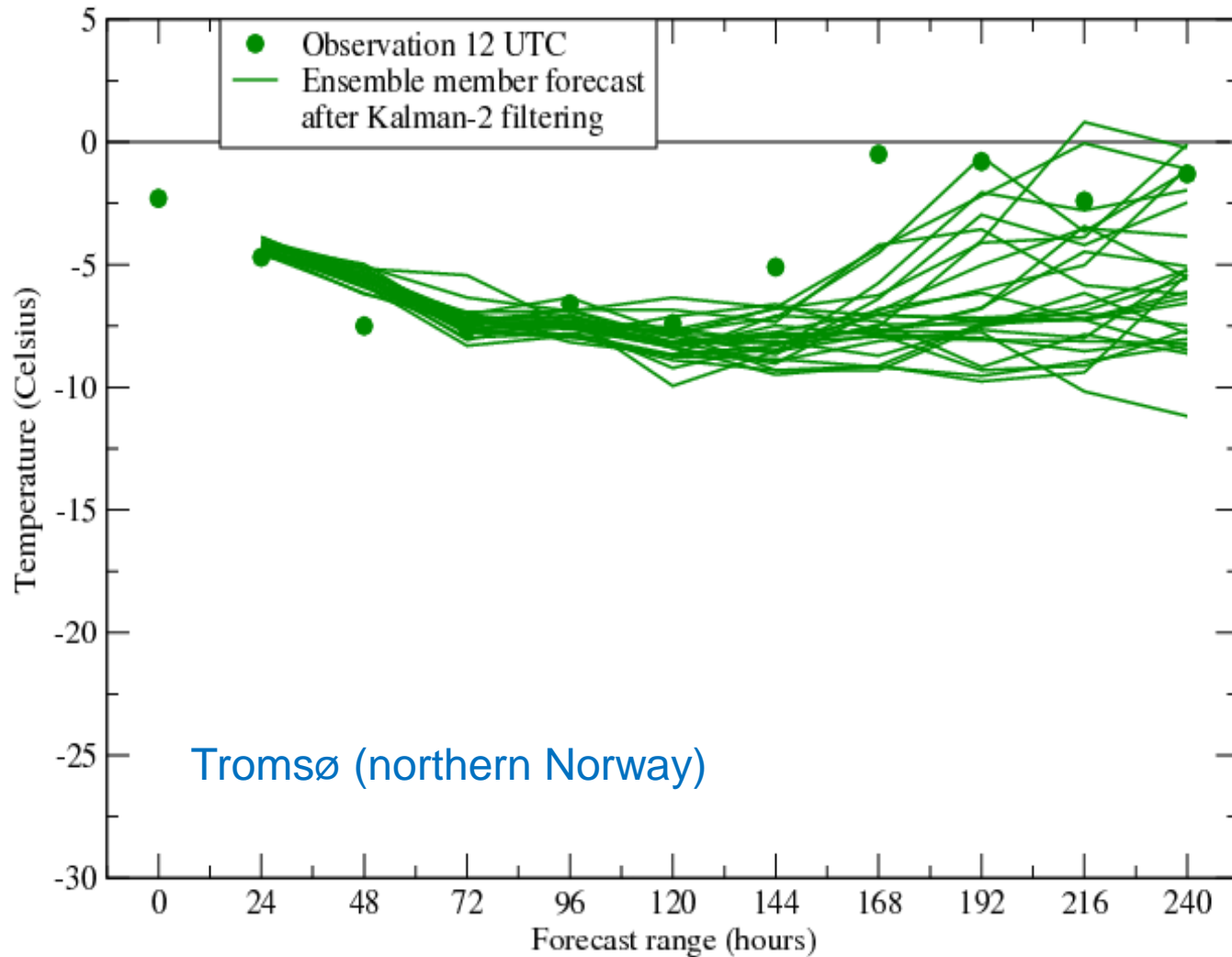


Statistical correction, calibration or interpretation:

A heavily biased temperature forecast



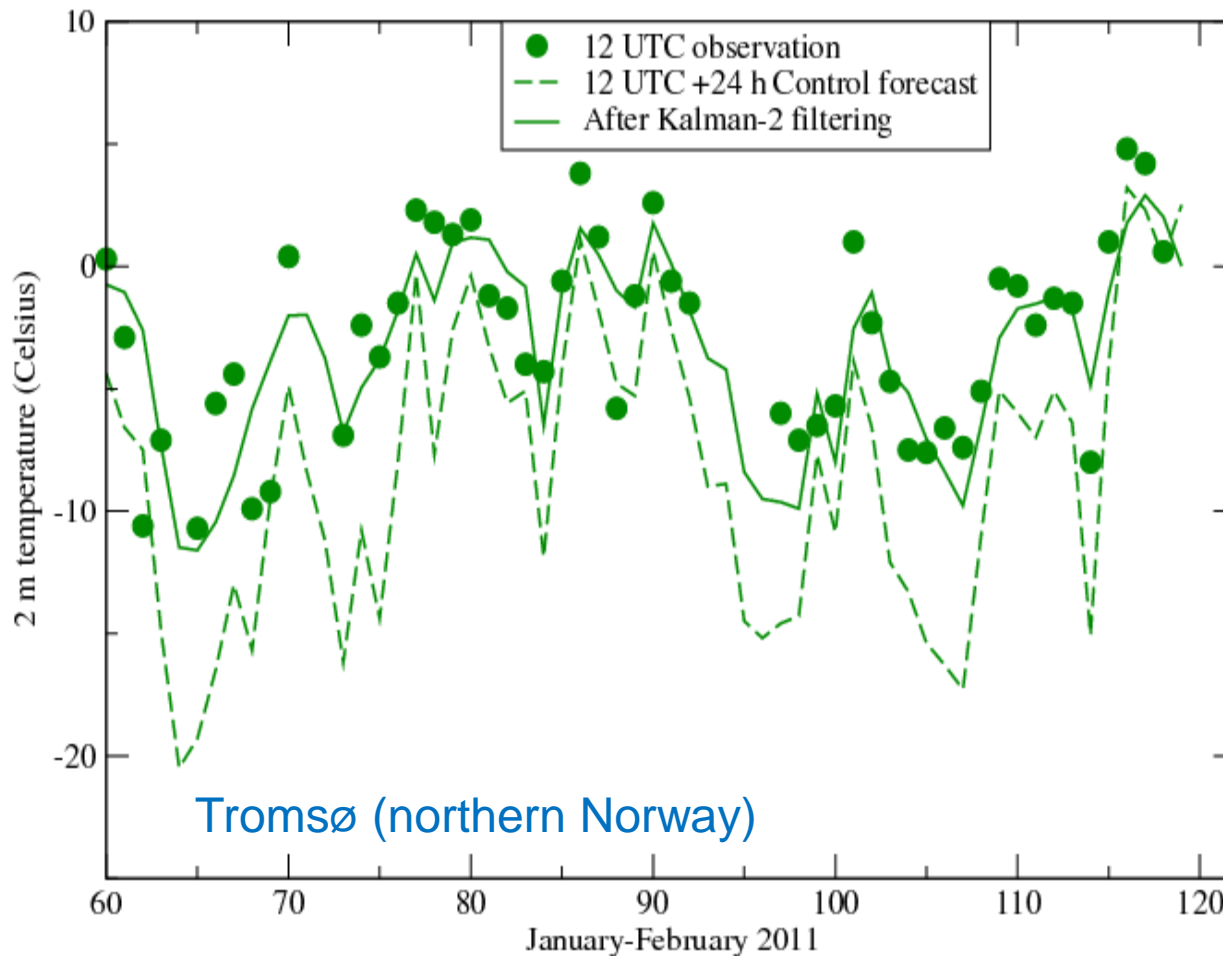
The EPS plume after statistical correction



The forecast (- - -) varies more than reality. The adaptive statistical filtering corrects for both mean error and over-variability

2-m temperature EPS forecast and Kalman-2 filtering

ECMWF EPS D+1 forecast for 01025 Tromso (Norway) winter 2011



No simple, straight bias. The mean error depends on the forecast

